Interpolation, Growth Conditions, and Stochastic Gradient Descent

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"Stochastic gradient descent (SGD) is today one of the main workhorses for solving large-scale supervised learning and optimization problems." —Drori and Shamir [2019]

... and also Agarwal et al. [2017], Assran and Rabbat [2020], Assran et al. [2018], Bernstein et al. [2018], Damaskinos et al. [2019], Geffner and Domke [2019], Gower et al. [2019], Grosse and Salakhudinov [2015], Hofmann et al. [2015], Kawaguchi and Lu [2020], Li et al. [2019], Patterson and Gibson [2017], Pillaud-Vivien et al. [2018], Xu et al. [2017], Zhang et al. [2016]

Stochastic gradient methods are the most popular algorithms for fitting ML models,

SGD:
$$w_{k+1} = w_k - \eta_k \nabla f_i(w_k).$$

But practitioners face major challenges with

- **Speed**: step-size/averaging controls convergence rate.
- Stability: hyper-parameters must be tuned carefully.
- Generalization: optimizers encode statistical tradeoffs.

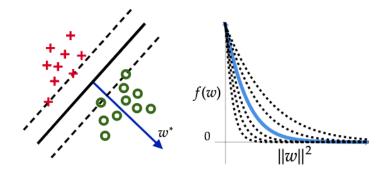
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Better Optimization via Better Models



Idea: exploit "over-parameterization" for better optimization.

- Intuitively, gradient noise goes to 0 if all data are fit exactly.
- No need for decreasing step-sizes or averaging.

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$$|\nabla f(w) - \nabla f(u)||_2 \le L ||w - u||_2 \qquad \forall w, u \in \mathbb{R}^d,$$

• (Sometimes) f is μ -strongly-convex: $\exists \mu > 0$ such that,

$$f(u) \ge f(w) + \langle \nabla f(w), u - w \rangle + \frac{\mu}{2} \|u - w\|_2^2 \quad \forall w, u \in \mathbb{R}^d.$$

Interpolation and Growth Conditions

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- 3. \mathcal{O} is **unbiased**, meaning

$$\mathbb{E}_{z_k}\left[f(w_k, z_k)\right] = f(w_k) \quad \text{and} \quad \mathbb{E}_{z_k}\left[\nabla f(w_k, z_k)\right] = \nabla f(w_k).$$

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4. $\mathcal O$ is individually-smooth, meaning $f(\cdot,z_k)$ is $L_{\max}\text{-}\mathsf{smooth},$

$$\|\nabla f(w, z_k) - \nabla f(u, z_k)\|_2 \le L_{\max} \|w - u\|_2 \quad \forall w, u \in \mathbb{R}^d,$$

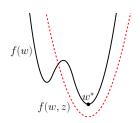
almost surely.

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Definition (Interpolation: Minimizers)

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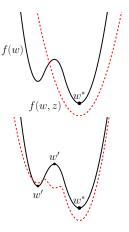
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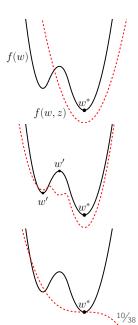
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Definition (Interpolation: Mixed)

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Strong Growth+Noise : $\mathbb{E}\left[\|\nabla f(w, z_k)\|^2\right] \le \rho \|\nabla f(w)\|^2 + \sigma^2.$

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 $\label{eq:strong} {\rm Strong} \ {\rm Growth}: \quad \mathbb{E}\left[\|\nabla f(w,z_k)\|^2 \right] \leq \rho \, \|\nabla f(w)\|^2.$

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Weak Growth : $\mathbb{E}\left[\|\nabla f(w, z_k)\|^2 \right] \leq \alpha \left(f(w) - f(w^*) \right).$

• Implies **mixed** interpolation.

Growth Conditions: Interpolation + Smoothness

Smoothness relates local and global behavior.

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Lemma (Interpolation and Weak Growth)

If minimizer interpolation holds, then weak growth also holds with

$$\alpha \leq \frac{L_{\max}}{L}.$$





Lemma (Interpolation and Strong Growth)

Assume f is μ strongly-convex. If minimizer interpolation holds, then strong growth also holds with

$$\rho \leq \frac{L_{\max}}{\mu}.$$

Stochastic Gradient Descent

Fixed Step-Size SGD

- 0. Choose an initial point $w_0 \in \mathbb{R}^d$.
- 1. For each iteration $k \ge 0$: 1.1 Query \mathcal{O} for $\nabla f(w_k, z_k)$.
 - 1.2 Update input as

$$w_{k+1} = w_k - \eta \nabla f(w_k, z_k).$$

Prior work for SGD under growth conditions or interpolation:

- Convergence under strong growth [Cevher and Vu, 2019, Schmidt and Le Roux, 2013, Solodov, 1998, Tseng, 1998].
- Convergence under weak growth [Vaswani et al., 2019a].
- Convergence under interpolation [Bassily et al., 2018].

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- Convergence under interpolation [Bassily et al., 2018].

We provide many improved results:

- **Bigger** step-sizes and **faster** rates for convex and strongly-convex objectives.
- Almost-sure convergence under weak/strong growth.
- Trade-offs between growth conditions and interpolation.

Assume f is convex and minimizer interpolation holds. Then SGD with $\eta=\frac{1}{L_{\max}}$ converges as

$$\mathbb{E}[f(\bar{w}_K)] - f(w^*) \le \frac{L_{\max}}{2K} \|w_0 - w^*\|^2.$$

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- Improves over worst-case rate with weak growth.
- If $L_{max} = L$, then guarantee is tight with deterministic GD!
- Otherwise, stochasticity worsens conditioning of problem.

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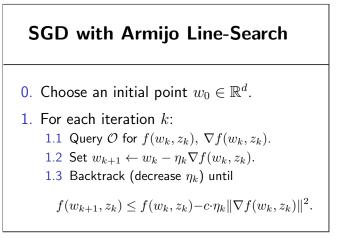
Is grid-search really the best way to pick η ?

376	
377	<pre>for i, step_size in enumerate(np.logspace(-4,1,12)):</pre>
378	opt_params["step_size"] = step_size
379	results[i] = run_experiment(opt_params, exp_params, data_params, model_fn,
380	objective, error_fn, training_set, test_set)
381	

SGD: the Armijo Line-search

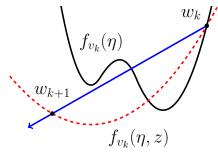
The Armijo line-search is a classic solution to step-size selection.

SGD with Armijo Line-search: Procedure



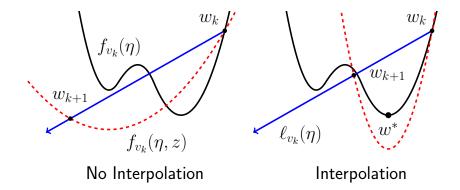
Note: Evaluates Armijo condition on $f(\cdot, z_k)$ instead of f and needs direct access to $f(\cdot, z_k)$ to backtrack.

SGD with Armijo Line-search: Visualization



No Interpolation

SGD with Armijo Line-search: Visualization



SGD with Armijo Line-search: Key Lemma

Lemma (Step-size Bound)

Assume minimizer interpolation holds.

Then the **maximal** step-size satisfying the stochastic Armijo condition satisfies the following:

$$\frac{2(1-c)}{L_{\max}} \le \eta_{\max} \le \frac{f(w_k, z_k) - f(w^*, z_k)}{c \|\nabla f(w_k, z_k)\|^2}.$$







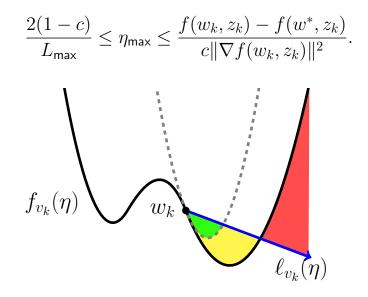




Comments:

- Mirrors classic result in deterministic optimization.
- Easy to relax to a backtracking line-search.

SGD with Armijo Line-Search: Lemma Geometry



Theorem (Convex + Interpolation)

Assume minimizer interpolation holds and $f(\cdot, z)$ is convex. Then SGD with the Armijo line-search and c = 1/2 converges as

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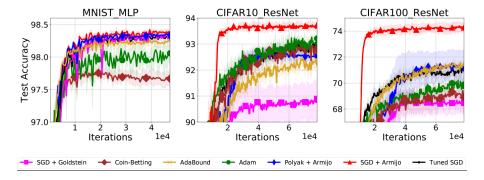
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 line-search is just as fast as the best constant step-size!
- Using the Armijo line-search is (nearly) parameter-free and recovers the deterministic rate when $L_{max} = L$.
- Strongly-convex f: we improve rate from $\bar{\mu}$ to μ .

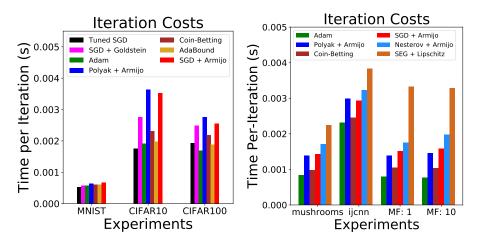
Painless SGD: Stochastic Armijo in Practice

Classification accuracy for ResNet-34 models trained on MNIST, CIFAR-10, and CIFAR-100.



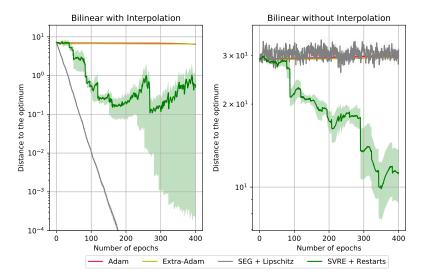
Painless SGD: Added Cost of Backtracking

Backtracking is low-cost and averages once per-iteration.



Painless SGD: Sensitivity to Assumptions

SGD with line-search is robust, but can still fail catastrophically.



²⁶/₃₈

Acceleration

SGD can be accelerated when minimizer interpolation holds:

• Liu and Belkin [2020] modify Nesterov's method and analyze convergence for strongly-convex functions.

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We follow Vaswani et al. [2019a] and close the convergence gap.

Strong growth implies a modified descent lemma,

$$\mathbb{E}_{z_k}[f(w_{k+1})] - f(w_k) \le \eta \left(1 - \frac{\rho L \eta}{2}\right) \|\nabla f(w_k)\|_2^2.$$

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Theorem (Acceleration)

Assume f is strongly convex and strong growth holds. Then stochastic acceleration with step-size $\eta = 1/\rho L$ converges as

$$\mathbb{E}\left[f(w_K)\right] - f(w^*) \le \left(1 - \sqrt{\frac{\mu}{\rho L}}\right)^K \left(f(w_0) - f(w^*) + \frac{\mu}{2}\delta_0\right).$$

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- Improves dependence from ρ to $\sqrt{\rho}$
 - Recall: $\sqrt{\rho} = \sqrt{\kappa_{\max}} = \sqrt{L_{\max}/\mu}$ in the worst case.

Takeaways

• **Interpolation**: the oracle model extends interpolation to general stochastic optimization problems.

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- **SGD**: improved rates show SGD under interpolation is tight with the deterministic setting.
- Line-Search: the Armijo line-search yields fast, parameter-free optimization under interpolation.
- Acceleration: stochastic acceleration is possible with a penalty of only $\sqrt{\rho}$.

Thanks for Listening!

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