

Accurate, Scalable Simulation of TinyOS Sensor Networks using Physically-Based Noise and Power Models

TAL RUSAK

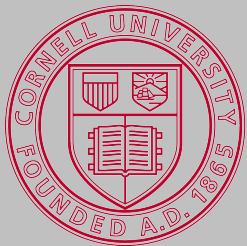
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Class of 2009

SIGSCE, ACM Student Member



Wireless Sensor Networks and TinyOS



- *Wireless sensor networks* are networks of small, low capacity, slow but low-powered devices (*motes*) that *collect information, communicate wirelessly, and make intelligent decisions* over long periods (months to years) without human intervention.
- TinyOS is a software layer that provides frameworks, components, and interfaces for use with sensor network motes.

P. Levis, "TinyOS: An Open Platform for Wireless Sensor Networks." Invited Tutorial, IEEE MDM, May 10, 2006.



- Open-source code: <http://www.tinyos.net/>

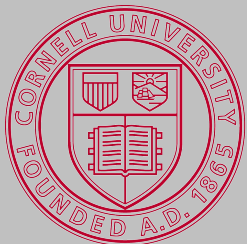
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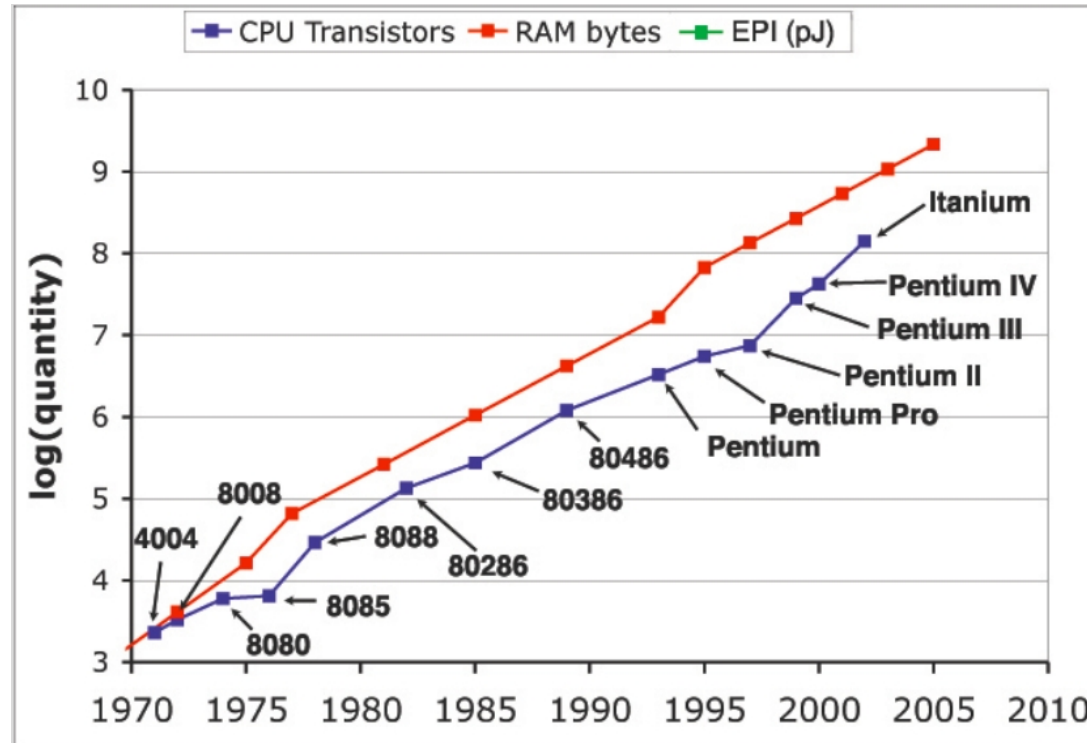
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Results



Past 40 years ...

- Focus of research and development in computing was to satisfy Moore's Law for processor speed and memory capacity.



P. Levis, "TinyOS: An Open Platform for Wireless Sensor Networks." Invited Tutorial, IEEE MDM, May 10, 2006.

- Computers (usually) tied to power source to remain operational over long periods.

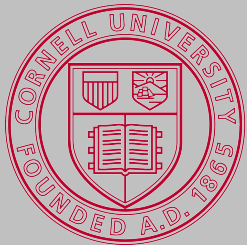
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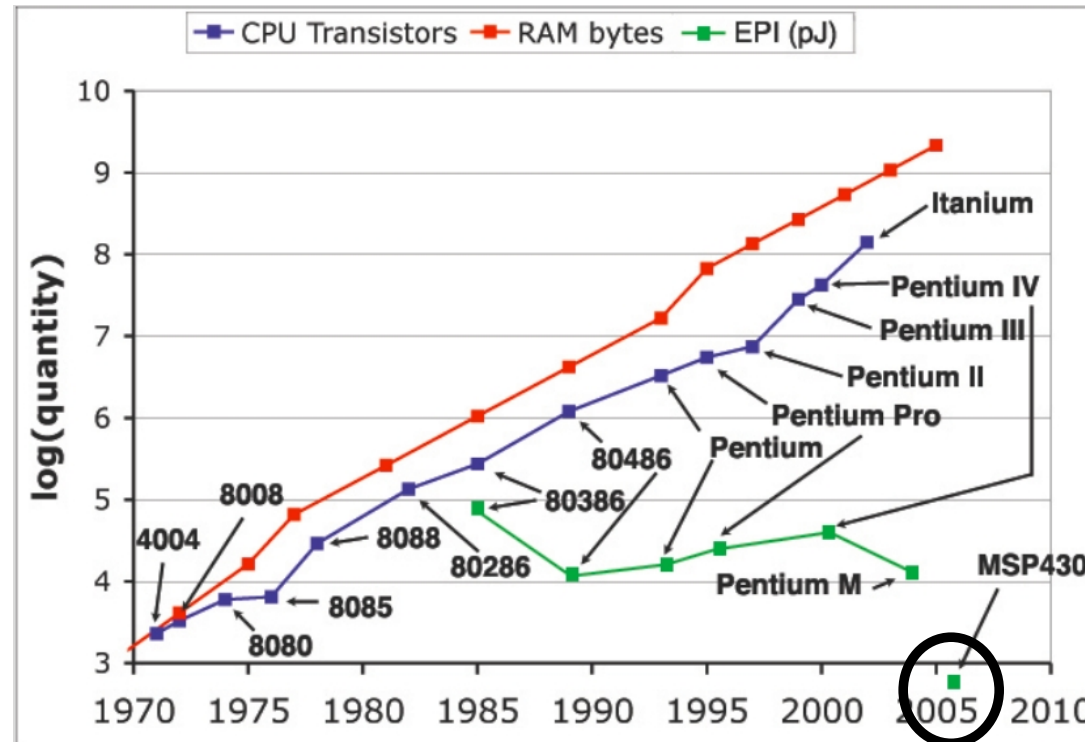
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Moore's Law with Power Consumption



- Highly distributed computing applications require low-power, long-life computers.



P. Levis, "TinyOS: An Open Platform for Wireless Sensor Networks." Invited Tutorial, IEEE MDM, May 10, 2006.

- Microcontrollers (e.g., MSP430) require an order of magnitude less power than typical processors.

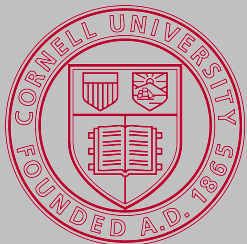
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Applications In Interdisciplinary Research ...



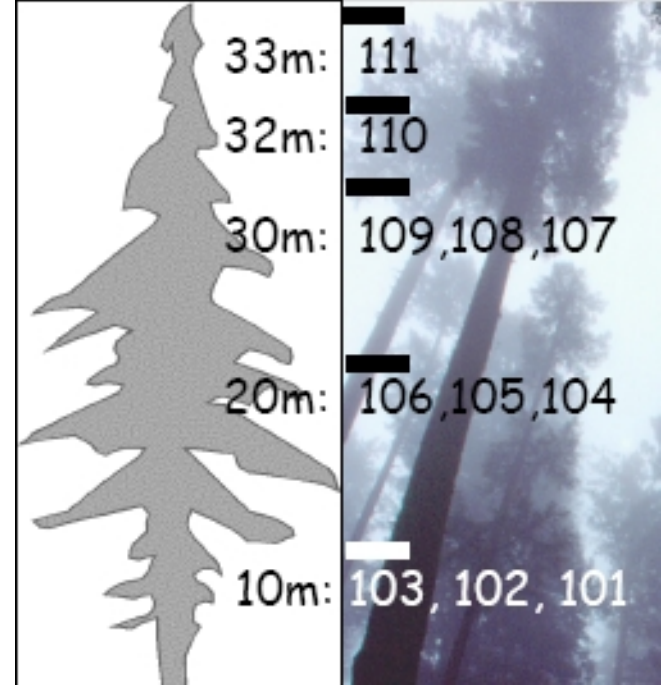
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http://www.wired.com/wired/archive/11.12/network_pr.html

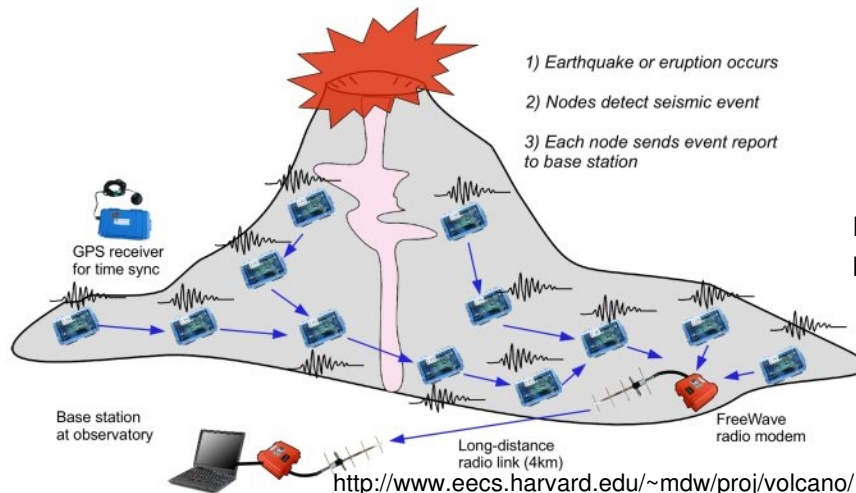
Biology: Great Duck
Island: Monitoring of
seabirds (2004)



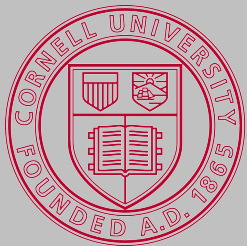
Ecology: Redwood
Microclimate Study
(2005)

P. Levis, "TinyOS: An Open Platform for Wireless Sensor Networks." Invited Tutorial, IEEE MDM, May 10, 2006.

Geology: Volcano
Monitoring (2006)



<http://www.eecs.harvard.edu/~mdw/proj/volcano/>



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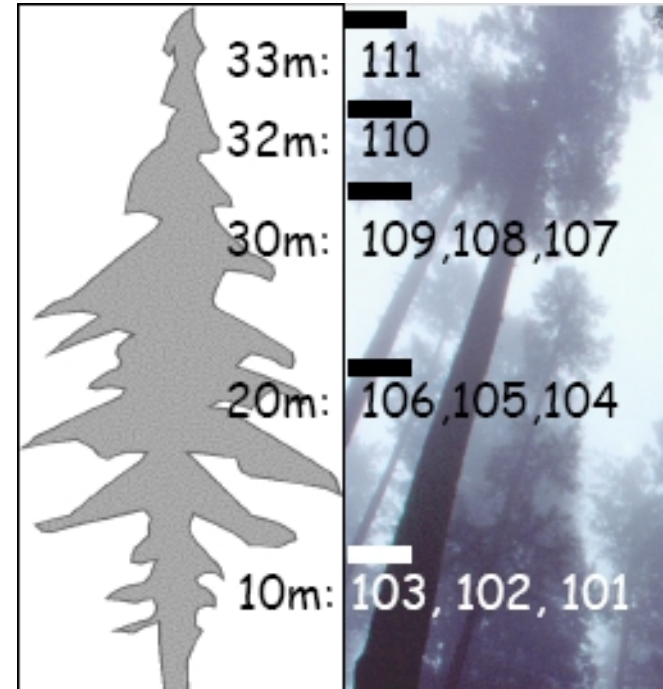
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... And Yield Success Rates



http://www.wired.com/wired/archive/11.12/network_pr.html

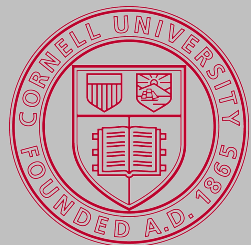
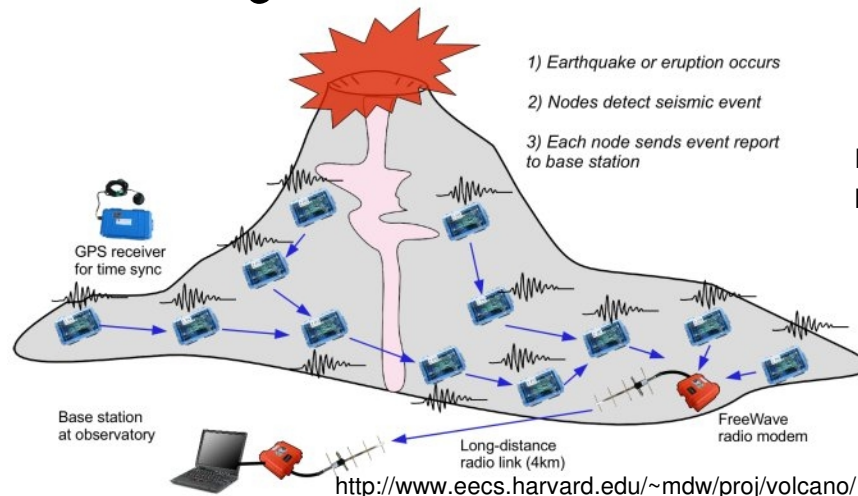
58% packet yield



40%

P. Levis, "TinyOS: An Open Platform for Wireless Sensor Networks." Invited Tutorial, IEEE MDM, May 10, 2006.

68%



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Simulation: Enabling Layer for Successful Sensor Network Applications



- Debugging sensor networks is difficult:
 - (1) Expensive, time consuming deployments in remote regions.
 - (2) Constrained resources (3 LEDs = 3 bits of debugging information displayed on typical motes).
 - (3) Little memory to keep detailed logs.
- **TOSSIM** is the **T**iny**O**S **S**IMulator.
- TOSSIM replaces several low level abstractions with PC-based equivalents, but otherwise uses the same code as TinyOS.
- The challenge is to effectively simulate radio links of wireless sensor networks.

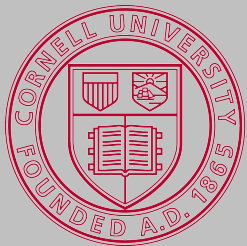
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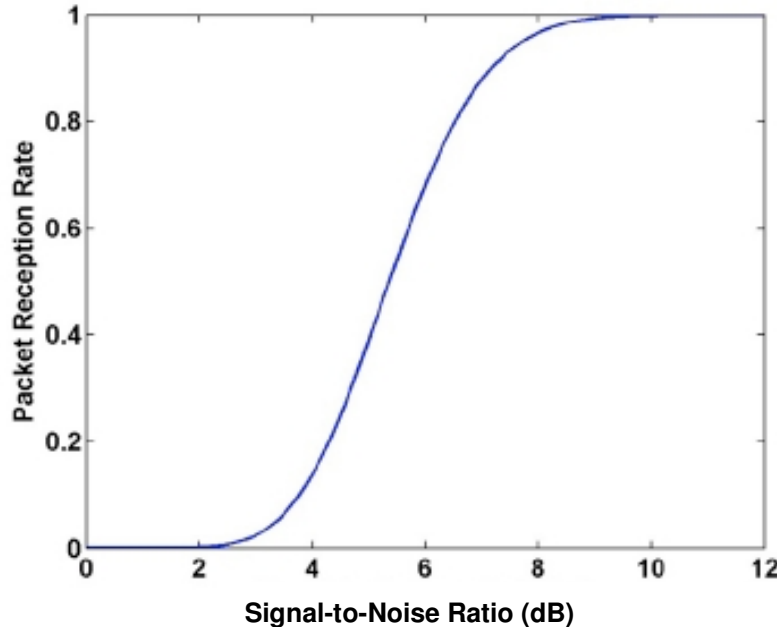
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Physically Based Simulation of Radio Links



- SNR curve for typical mote radio (CC2420):



HyungJune Lee, Alberto Cerpa, and Philip Levis, "Improving Wireless Simulation Through Noise Modeling." In Proceedings of the IPSN, 2007.

- $\text{SNR} = \text{Signal Power} - \text{Noise}$ (logarithmic scale)
- Packet reception probability can be determined using the SNR value and the above curve.
- The challenge is to predict Signal Power (**S**) and Noise (**N**).

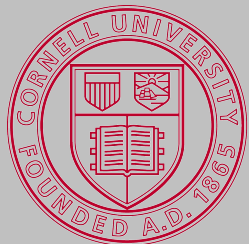
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TOSSIM 2.0.1 (2007)

Implementation



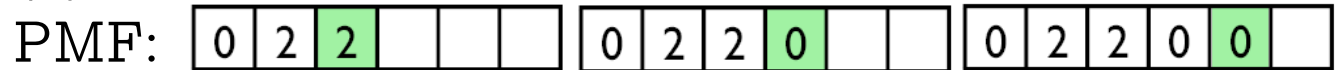
- TOSSIM 2.0.1 models *noise* by using the Concurrent Pattern Matching (CPM) algorithm:
 - (1) Input and pre-process an experimental trace:



signature	0	1	2	9
00	33%	33%	33%	0%
01	0%	100%	0%	0%
02	0%	33%	33%	33%
11	0%	66%	33%	0%
12	100%	0%	0%	0%
20	66%	0%	33%	0%
21	0%	0%	100%	0%
22	100%	0%	0%	0%

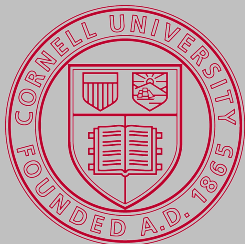
$k = \text{History size} = 2$

- (2) Take k traces from experiment; then sample



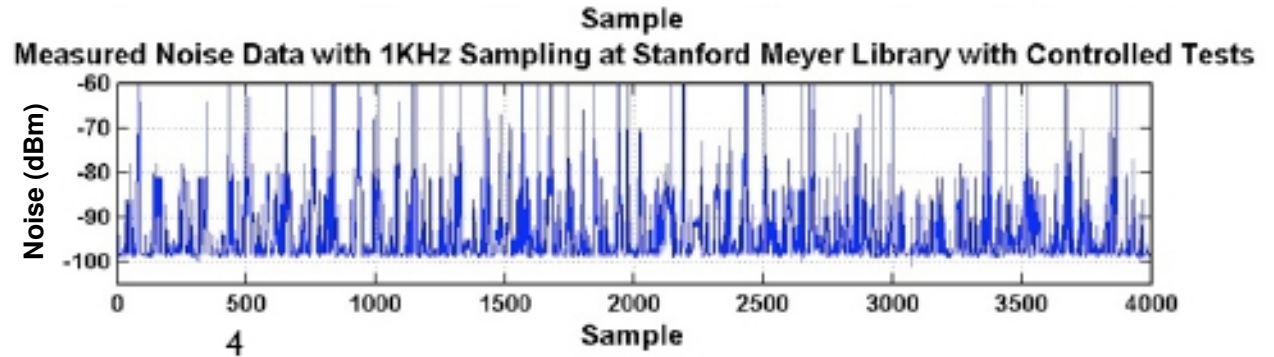
HyungJune Lee, Alberto Cerpa, and Philip Levis, "Improving Wireless Simulation Through Noise Modeling." In Proceedings of the IPSN, 2007.

- TOSSIM 2.0.1 assumes *signal power* to be constant and user-defined.



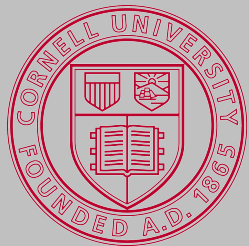
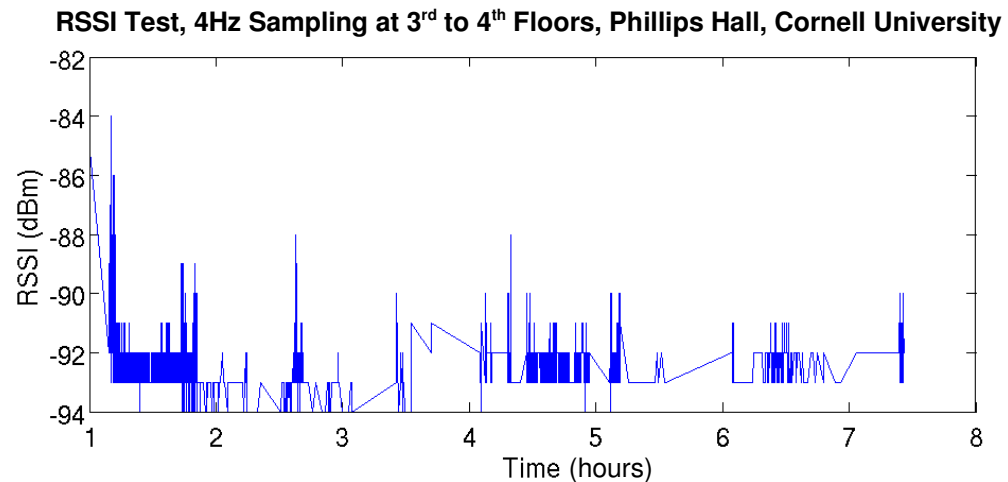
Power and Noise Variations

- Noise:



HyungJune Lee, Alberto Cerpa, and Philip Levis, "Improving Wireless Simulation Through Noise Modeling." In Proceedings of the IPSN, 2007.

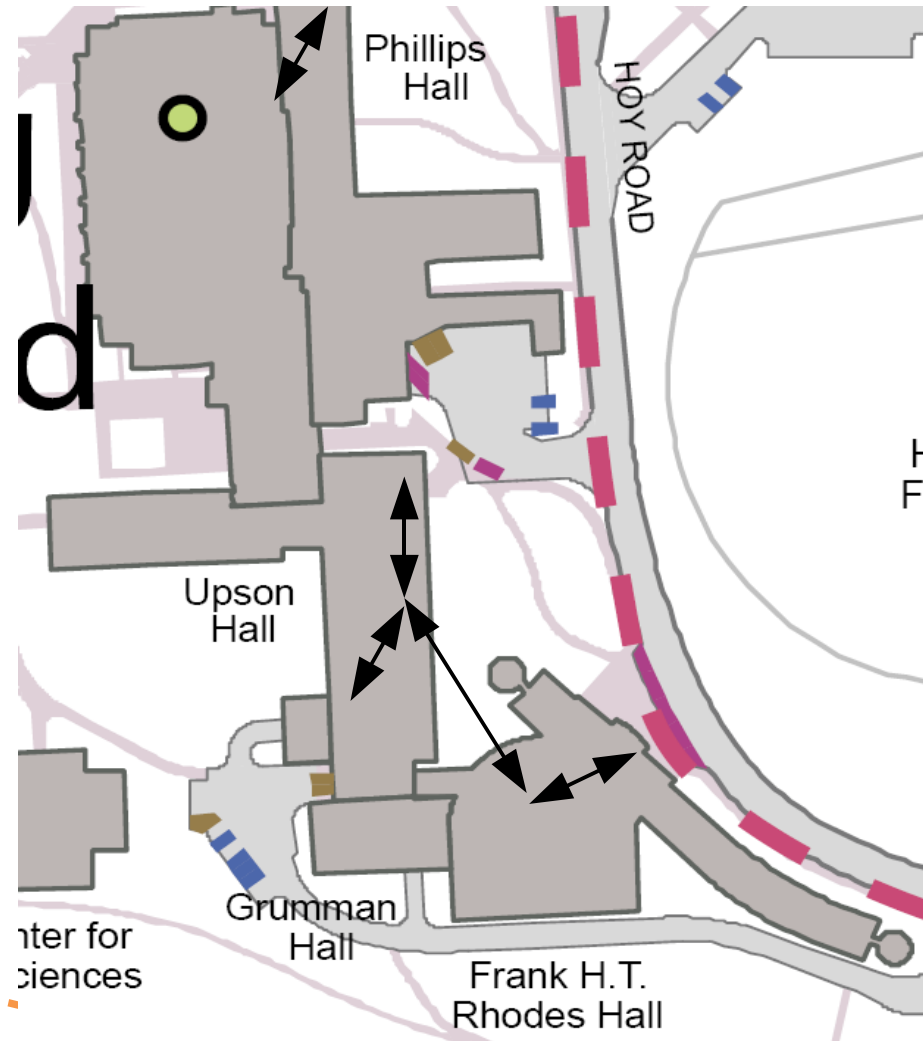
- RSSI \approx Signal Power:



Experiments Collected



- Signal power is a property of a link between two positions, not a property of the individual position.



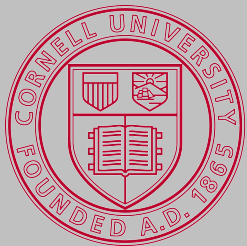
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Challenges of Collecting Power Traces



- *Idea:* Collect a signal power trace and use CPM to model signal power.
- Collecting power traces is more complex than collecting noise traces, since:
 - (1) Signal power can only be approximated by sampling the RSSI register:

- Let \mathbf{S} be the signal wave and \mathbf{N} be the resultant wave from the sum of all noise waves in an environment.

Then

$$RSSI \text{ (dBm)} = |\mathbf{S} + \mathbf{N}| \text{ and}$$

$$\text{Signal power} = |\mathbf{S}| = |RSSI - \mathbf{N}|$$

where $\mathbf{S} + \mathbf{N}$ and $RSSI - \mathbf{N}$ consider wave phases.

- (2) If a packet is lost in transmission, then even the RSSI estimate is not possible.

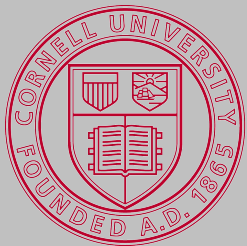
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Expected Value PMF Algorithm



- Average noise = -90 dBm

Power trace: -82 _ -87 -85 _ -86 -82 _ -81 _

SNR: 8 ? ? 3 5 ? 4 8 ? 9 ?

PRR: .99 ? ? .1 .4 ? .2 .99 ? 1.0 ?

Expected lost: 0 ? ? 9 1.5 ? 4 0 ? 0 ?

Actual lost packets: 5; Expected lost packets: 14.5

- Fill in the gaps by sampling from the unfilled packet distribution:

Power Value: -81 -82 -85 -86 -87

Remaining to fill: 0 0 1.5 4 9 (total 14.5)

% of those remaining: 0% 0% 10.3% 27.6% 62.1%

- Filled in trace (one possible variation):

-82 -87 -86 -87 -85 -87 -86 -82 -87 -81 -85

- Run CPM on this trace to determine the Power value at any time.

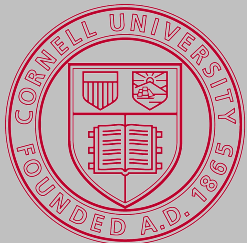
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Average Power Algorithm



Power trace: -82 _ _ -87 -85 _ -86 -82 _ -81 _

- Average power (rounded to integer) = -84 dBm
- Fill the power trace with average power value.

- Filled in trace:

-82 -84 -84 -87 -85 -84 -86 -82 -84 -81 -84

- Run CPM on this trace to determine the Power value at any time.

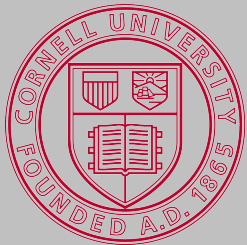
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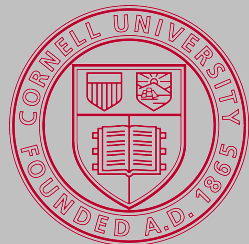
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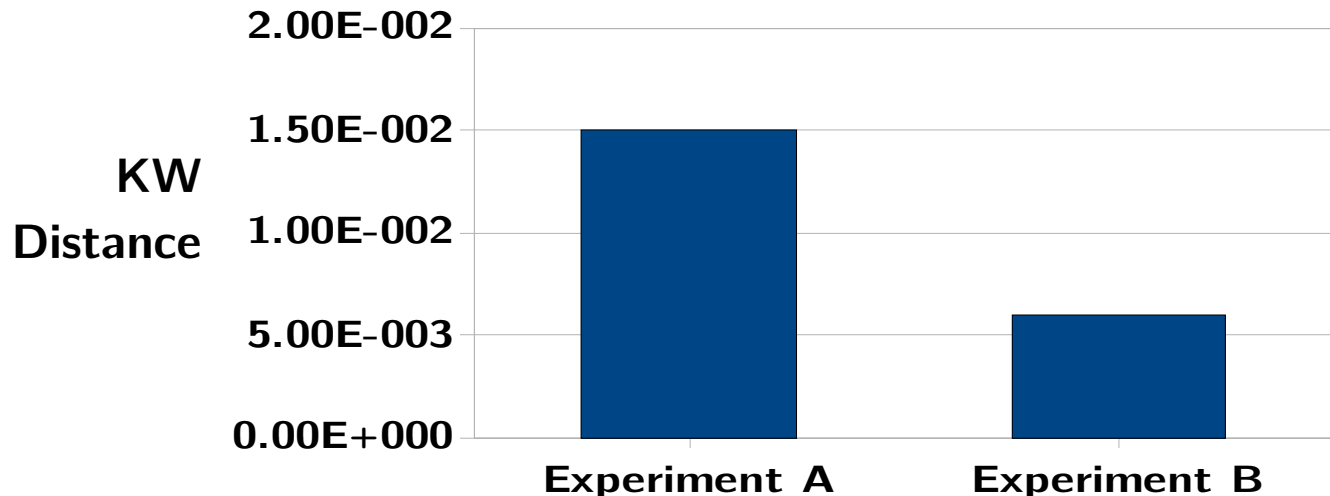




CPM is Effective for Modeling Power: KW Distance



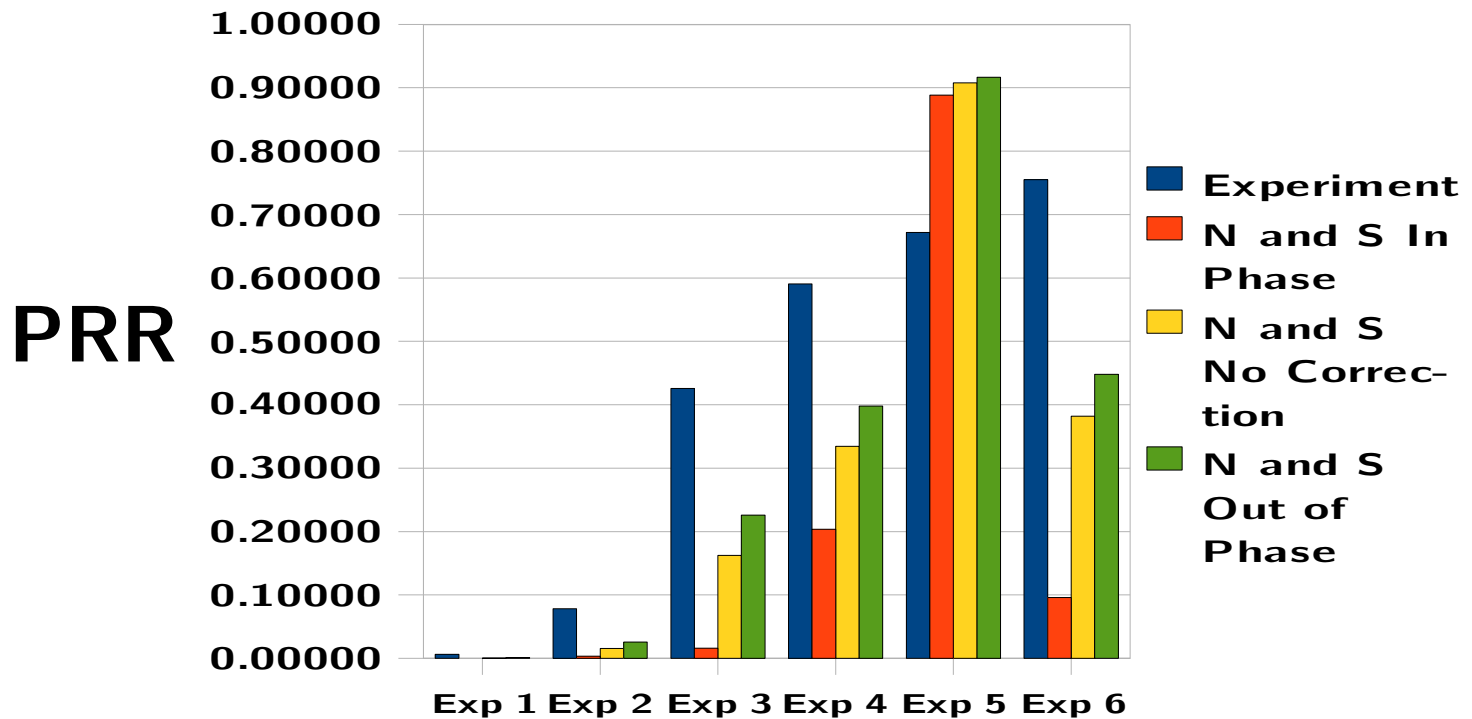
- Kantorovich-Wasserstein (KW) distance is a formal quantification of the effectiveness of the CPM algorithm on a given experimental trace.
- KW Distances on the order of 10^{-2} or lower are excellent.
- Representative examples:



Impact of Phase Differences in Expected Value PMF Algorithm



- One of the first comparisons of TOSSIM simulations to real experiments.



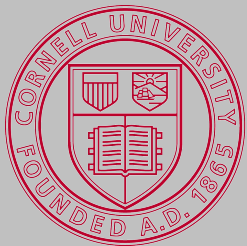
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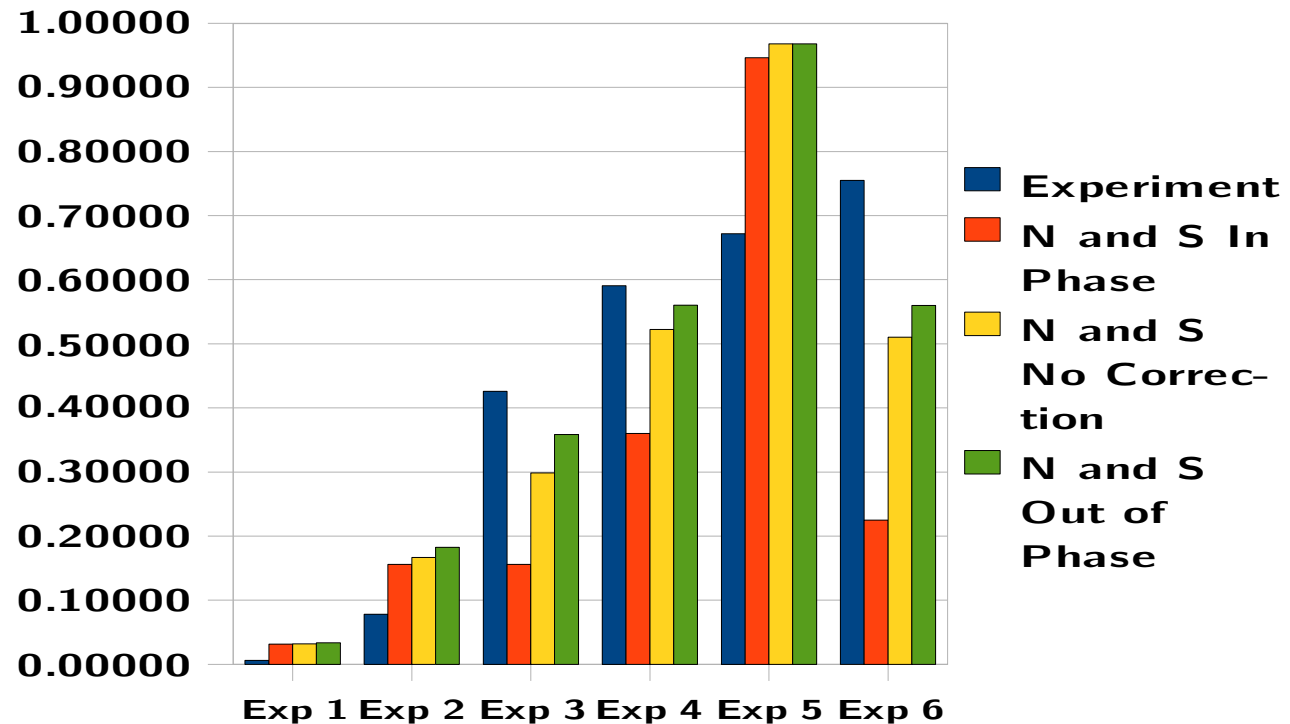


Impact of Phase Differences in Average Power Algorithm



- One of the first comparisons of TOSSIM simulations to real experiments.

PRR



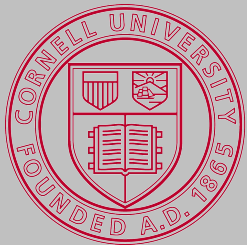
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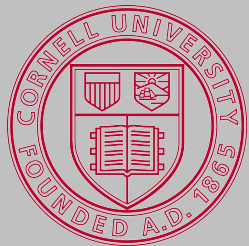
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Conclusions



- As expected, different assumptions work more effectively for different experiments.
- This observation corresponds to reality, since the phase of noise waves may differ in different environments and packets are lost for different reasons.
- *Future work:* Development of an automated optimization layer to predict the most reasonable assumptions for a given environment.
- *Future work:* I aim to develop theoretical models based on the information obtained from these studies in simulation.

Simulation of TinyOS Sensor Networks

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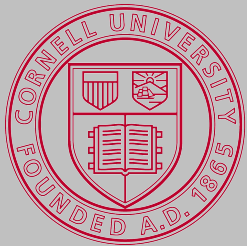
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Thank you.

Questions?



CPM Model for Trace Histories

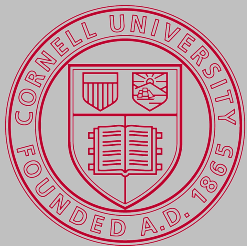


- Scan noise trace, keeping a history of size k .
- For each signature of k prior noise readings, construct the probability distribution for the next reading.

0 2 1 2 0 2 2 0 0 1 1 1 1 2 0 0 0 2 9 0

signature	0	1	2	9
00	33%	33%	33%	0%
01	0%	100%	0%	0%
02	0%	33%	33%	33%
11	0%	66%	33%	0%
12	100%	0%	0%	0%
20	66%	0%	33%	0%
21	0%	0%	100%	0%
22	100%	0%	0%	0%

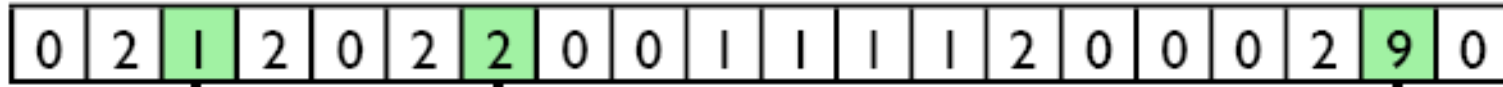
$$k = 2$$



CPM Model for Trace Histories



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- For each signature of k prior noise readings, construct the probability distribution for the next reading.



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00	33%	33%	33%	0%
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$$k = 2$$

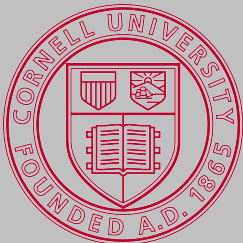
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CPM Sampling Demo



signature	0	1	2	9
00	33%	33%	33%	0%
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11	0%	66%	33%	0%
12	100%	0%	0%	0%
20	66%	0%	33%	0%
21	0%	0%	100%	0%
22	100%	0%	0%	0%

$$k = 2$$

30

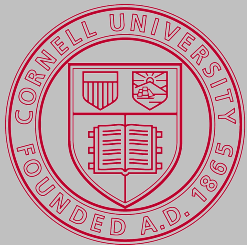
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CPM Sampling Demo



signature	0	1	2	9
00	33%	33%	33%	0%
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20	66%	0%	33%	0%
21	0%	0%	100%	0%
22	100%	0%	0%	0%

$$k = 2$$

31

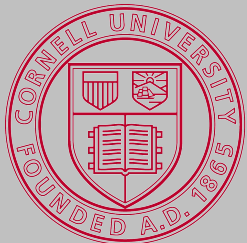
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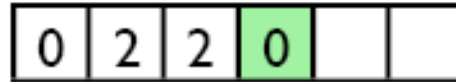
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CPM Sampling Demo



signature	0	1	2	9
00	33%	33%	33%	0%
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20	66%	0%	33%	0%
21	0%	0%	100%	0%
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$$k = 2$$

32

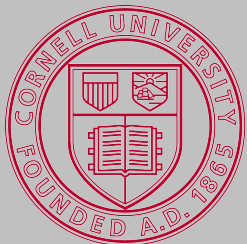
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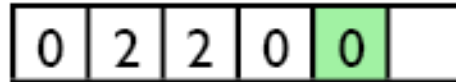
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CPM Sampling Demo



signature	0	1	2	9
00	33%	33%	33%	0%
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33

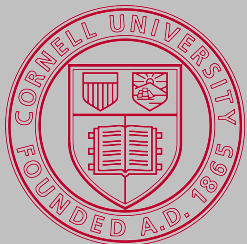
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CPM Sampling Demo



0 2 2 0 0 1

signature	0	1	2	9
00	33%	33%	33%	0%
01	0%	100%	0%	0%
02	0%	33%	33%	33%
11	0%	66%	33%	0%
12	100%	0%	0%	0%
20	66%	0%	33%	0%
21	0%	0%	100%	0%
22	100%	0%	0%	0%

$k = 2$

34

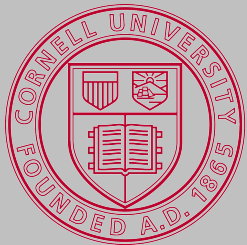
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CPM Sampling Result



- Modeled trace is not the same as the experimental trace:

0	2	2	0	0	1
---	---	---	---	---	---

0	2	1	2	0	2	2	0	0	1	1	1	1	2	0	0	0	2	9	0
---	---	---	---	---	---	---	---	---	---	---	---	---	---	---	---	---	---	---	---

- This increases the randomness of simulation output and thus decreases the predictability of the simulation.
- This allows for substantial representative simulation.

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