

## Reproducing Kernel Hilbert Spaces and Kernel-based Learning Methods (1 of 2)

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## 1 Kernel-based Learning Algorithms

Kernel-based Learning Algorithms are used in data analysis and machine learning. There are several types of learning mechanism:

- Unsupervised Learning - No teacher/ labels
- Supervised Learning - Teachers/ labels
- Semi-supervised Learning - The labels might be expensive and only some data point has labels.
- Online Learning - Time Series Data

## 2 Kernel-based Method

- A way to model a much larger class of data using a vector space model.
- A lot more descriptive flexibility without much additional computational cost.

The kernel method involves a mapping into a high (possibly infinite) dimensional space.

$$\phi(X) : X \rightarrow F$$

Given a set of vector  $x_i \in \mathbf{R}$ , we define the Gram matrix  $G$ :

$$G_{ij} = x_i^T x_j$$

which is a symmetric matrix of inner products.

**Definition** Given a matrix  $G$ , we say  $G$  is positive semi-definite if for all vectors  $x$ , we have  $x^T G x \geq 0$ .

We can also generalize the concept of positive number to a partial ordering on matrices. To compare two matrices  $A, B$ , we can check if  $A - B$  is positive semi-definite.

In  $\mathbf{R}^n$ , any Gram matrix is positive semi-definite. Also, any positive semi-definite matrix is a Gram matrix for some set of vectors.

**Note** The set of vectors that generates a certain Gram matrix is not unique.

### 3 Supervised Learning - Classification

There are different ways to formalize this. One way is to say the data are  $(x_i, y_i)_{i=1}^n \in \mathbf{R}^N \times Y$ , where  $Y = \{-1, 1\}$ . Then the goal is to find a function  $f : \mathbf{R}^N \rightarrow Y$  such that if given a new example, it will classify it correctly. For example, we can say

$$\begin{cases} f(x) > 0 & \rightarrow \text{assign } 1 \\ f(x) < 0 & \rightarrow \text{assign } -1 \end{cases}$$

Question: What if the data is more representable as a graph?

#### 3.1 Risk Minimization

Given some training data  $(x_i, y_i)_{i=1}^n$  and also test data drawn from the same distribution  $P(x, y)$ , our goal is to find the best function  $f$  from what we already know:

- $(x_i, y_i)_{i=1}^n$
- a function class  $I$  to optimize over

We want to minimize the risk/error defined by

$$R[f] = \int L(f(x), y) dP(x, y)$$

where  $L$  denotes some loss function.

Our goal is to minimize  $R[f]$  subject to bias/variance trade-off while having flexibility generally.

#### 3.2 Empirical Risk Minimization (ERM)

The empirical risk is defined on the test data set:

$$R_{emp}[f] = \frac{1}{n} \sum_{i=1}^n L(f(x_i), y_i)$$

and we hope that if  $n \rightarrow \infty$ , we would have  $R_{emp}[f] \rightarrow R[f]$ .

#### 3.3 Structural Risk Minimization

The idea is to restrict ourselves to some nice function class and do ERM with the following procedures:

1. Construct a nested family of function class

$$F_1 \subset F_2 \subset \dots \subset F_k$$

2. Let  $f_1, \dots, f_k$  be the ERM solutions in  $F_k$
3. Choose  $(k^*, F_{k^*}, f_{k^*})$  such that upper bound on generalization error is minimized.

**Theorem** Let  $h$  be the VC dimension of  $I$ . Then  $\forall \delta > 0, f \in I$

$$R[f] \leq R_{emp}[f] + \sqrt{\frac{h(\ln(\frac{2n}{h} + 1)) - \ln(\delta/4)}{n}}$$

with probability  $(1 - \delta), \forall n > h$

**Note** The above bound represents a bias/variance trade-off. It doesn't not depend on  $P(x, y)$ . The main reason to use this bound is that we cannot compute the LHS, but given any  $h$ , we can compute the RHS.

### 3.4 VC dimension

**Definition** A *dichotomy* of set  $S$  is a partition of  $S$  into two disjoint pieces.

**Definition** A set of points  $S$  is *shattered* by a hypothesis space  $\mathcal{H}$  if for all dichotomy of  $S, \exists$  a hypothesis  $h \in \mathcal{H}$  consistent with the dichotomy.

**Definition** The *VC dimension* of  $\mathcal{H}$  over given set of points  $S$  is the size of the largest subset of  $S$  shattered by  $\mathcal{H}$ .

The point is that the complexity of a classifier does not depend on the size of  $\mathcal{H}$ , but on how it performs on  $S$ .

**Note** To show that the VC dimension of  $\mathcal{H}$  is  $\geq d$ . View it as a game:

- (1) I choose  $d$  points.
- (2) The adversary chooses labels from  $\{-1, 1\}$ .
- (3) I produce a hypothesis  $h \in \mathcal{H}$ .

The VC dimension is the maximum of such  $d$ .

**Note** The VC dimension is powerful to bound certain things, but

- (1) it can be hard to work with.
- (2) it is suboptimal bound.
- (3) it is a distribution-independent bound.

### 3.5 Hyperplane

**Definition** *Hyperplane* is a set of  $\mathcal{H}$  in  $\mathbb{R}^n$  that is “nice” and has the following form:  $\langle \mathbf{w}, \mathbf{x} \rangle + b = 0$ . The decision boundary of a hyperplane is  $\text{sign}(\langle \mathbf{w}, \mathbf{x} \rangle + b)$ .

**Claim** In  $\mathbb{R}^2$ , I can find 3 points such that I can shatter with a hyperplane, but I can not find 4. The general result is that given  $m$  points in  $\mathbb{R}^n$ , they can be shattered by oriented hyperplane if and only if the points we have are linearly independent.

**Claim** The VC dimension of oriented hyperplane in  $\mathbb{R}^n$  is  $n + 1$ .

**Definition** We say the data  $\{\mathbf{x}_i, y_i\}_{i=1}^n$  are *linearly separable* if  $\exists\{\mathbf{w}, b\}$  such that  $\langle \mathbf{w}, \mathbf{x} \rangle + b = 0$  separates the data, i.e.

$$\begin{aligned} \mathbf{x}_i \cdot \mathbf{w} + b &\geq 1 & \text{if } y_i = 1 \\ \mathbf{x}_i \cdot \mathbf{w} + b &\leq -1 & \text{if } y_i = -1 \end{aligned}$$

**Definition** Let  $d_+$  ( $d_-$ ) be the shortest distance from the separating hyperplane to a data point with + (-) label. The *margin* of the separating hyperplane w.r.t. the data is  $d_+ + d_-$ . If  $\mathbf{w}$  is the weight vector, then  $d_+ = d_- = 1/\|\mathbf{w}\|$ , so the margin  $\gamma = 2/\|\mathbf{w}\|$ .

**Fact** Let  $\mathcal{H}$  be the set of linear classifiers, and  $\mathcal{H}_\gamma$  be the set of linear classifiers with margin  $\gamma$ . Intuitively,  $\mathcal{H}_\gamma$  is smaller than  $\mathcal{H}$ . Let  $R$  be the radius of the smallest inclosing ball of the data, then

$$VC(\mathcal{H}_\gamma) \leq R^2 \mathbf{w} \cdot \mathbf{w} + 1, \tag{1}$$

independent of dimension.

### 3.6 Support Vector Machines (SVM)

The fact in (1) suggests optimizing the margin (SVM). Given  $\{\mathbf{x}_i, y_i\} \in \mathbb{R}^N \times \{-1, 1\}$ , find a good classification hyperplane given by the following optimization problem:

$$\begin{aligned} \min_{\mathbf{w}, b} \quad & \frac{1}{2} \|\mathbf{w}\|_2^2 \\ \text{Subject to} \quad & y_i (\langle \mathbf{w}, \mathbf{x} \rangle + b) \geq 1. \end{aligned} \tag{2}$$

We can write (2) as an unconstrained problem with the Lagrange multipliers. Define

$$L(\mathbf{w}, b, \alpha) = \frac{1}{2} \|\mathbf{w}\|_2^2 - \sum_i \alpha_i (y_i (\langle \mathbf{w}, \mathbf{x} \rangle + b) - 1),$$

then (2) becomes

$$\min_{\mathbf{w}, b} \max_{\alpha > 0} L(\mathbf{w}, b, \alpha) \tag{3}$$

We can view (3) as a two player game

- (1) If player *A* violates the constraint in (2), then player *B* can choose  $\alpha$  such that the maximum goes to  $\infty$ .
- (2) If player *A* satisfies the constraint in (2), then player *B* chooses  $\alpha_i = 0$ .