

Reproducing Kernel Hilbert Spaces and Kernel-based Learning Methods (1 of 2)

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1 Kernel-based Learning Algorithms

Kernel-based Learning Algorithms are used in data analysis and machine learning. There are several types of learning mechanism:

- Unsupervised Learning - No teacher/ labels
- Supervised Learning - Teachers/ labels
- Semi-supervised Learning - The labels might be expensive and only some data point has labels.
- Online Learning - Time Series Data

2 Kernel-based Method

- A way to model a much larger class of data using a vector space model.
- A lot more descriptive flexibility without much additional computational cost.

The kernel method involves a mapping into a high (possibly infinite) dimensional space.

$$\phi(X) : X \rightarrow F$$

Given a set of vector $x_i \in \mathbf{R}$, we define the Gram matrix G :

$$G_{ij} = x_i^T x_j$$

which is a symmetric matrix of inner products.

Definition Given a matrix G , we say G is positive semi-definite if for all vectors x , we have $x^T G x \geq 0$.

We can also generalize the concept of positive number to a partial ordering on matrices. To compare two matrices A, B , we can check if $A - B$ is positive semi-definite.

In \mathbf{R}^n , any Gram matrix is positive semi-definite. Also, any positive semi-definite matrix is a Gram matrix for some set of vectors.

Note The set of vectors that generates a certain Gram matrix is not unique.

3 Supervised Learning - Classification

There are different ways to formalize this. One way is to say the data are $(x_i, y_i)_{i=1}^n \in \mathbf{R}^N \times Y$, where $Y = \{-1, 1\}$. Then the goal is to find a function $f : \mathbf{R}^N \rightarrow Y$ such that if given a new example, it will classify it correctly. For example, we can say

$$\begin{cases} f(x) > 0 & \rightarrow \text{assign } 1 \\ f(x) < 0 & \rightarrow \text{assign } -1 \end{cases}$$

Question: What if the data is more representable as a graph?

3.1 Risk Minimization

Given some training data $(x_i, y_i)_{i=1}^n$ and also test data drawn from the same distribution $P(x, y)$, our goal is to find the best function f from what we already know:

- $(x_i, y_i)_{i=1}^n$
- a function class I to optimize over

We want to minimize the risk/error defined by

$$R[f] = \int L(f(x), y) dP(x, y)$$

where L denotes some loss function.

Our goal is to minimize $R[f]$ subject to to bias/variance trade-off while having flexibility generally.

3.2 Empirical Risk Minimization (ERM)

The empirical risk is defined on the test data set:

$$R_{emp}[f] = \frac{1}{n} \sum_{i=1}^n L(f(x_i), y_i)$$

and we hope that if $n \rightarrow \infty$, we would have $R_{emp}[f] \rightarrow R[f]$.

3.3 Structural Risk Minimization

The idea is to restrict ourselves to some nice function class and do ERM with the following procedures:

1. Construct a nested family of function class

$$F_1 \subset F_2 \subset \dots \subset F_k$$

2. Let f_1, \dots, f_k be the ERM solutions in F_k
3. Choose (k^*, F_{k^*}, f_{k^*}) such that upper bound on generalization error is minimized.

Theorem Let h be the VC dimension of I . Then $\forall \delta > 0, f \in I$

$$R[f] \leq R_{emp}[f] + \sqrt{\frac{h(\ln(\frac{2n}{h} + 1)) - \ln(\delta/4)}{n}}$$

with probability $(1 - \delta), \forall n > h$

Note The above bound represents a bias/variance trade-off. It doesn't not depend on $P(x, y)$. The main reason to use this bound is that we cannot compute the LHS, but given any h , we can compute the RHS.

3.4 VC dimension

Definition A *dichotomy* of set S is a partition of S into two disjoint pieces.

Definition A set of points S is *shattered* by a hypothesis space \mathcal{H} if for all dichotomy of S , \exists a hypothesis $h \in \mathcal{H}$ consistent with the dichotomy.

Definition The *VC dimension* of \mathcal{H} over given set of points S is the size of the largest subset of S shattered by \mathcal{H} .

The point is that the complexity of a classifier does not depend on the size of \mathcal{H} , but on how it performs on S .

Note To show that the VC dimension of \mathcal{H} is $\geq d$. View it as a game:

- (1) I choose d points.
- (2) The adversary chooses labels from $\{-1, 1\}$.
- (3) I produce a hypothesis $h \in \mathcal{H}$.

The VC dimension is the maximum of such d .

Note The VC dimension is powerful to bound certain things, but

- (1) it can be hard to work with.
- (2) it is suboptimal bound.
- (3) it is a distribution-independent bound.

3.5 Hyperplane

Definition *Hyperplane* is a set of \mathcal{H} in \mathbb{R}^n that is “nice” and has the following form: $\langle \mathbf{w}, \mathbf{x} \rangle + b = 0$. The decision boundary of a hyperplane is $\text{sign}(\langle \mathbf{w}, \mathbf{x} \rangle + b)$.

Claim In \mathbb{R}^2 , I can find 3 points such that I can shatter with a hyperplane, but I can not find 4. The general result is that given m points in \mathbb{R}^n , they can be shattered by oriented hyperplane if and only if the points we have are linearly independent.

Claim The VC dimension of oriented hyperplane in \mathbb{R}^n is $n + 1$.

Definition We say the data $\{\mathbf{x}_i, y_i\}_{i=1}^n$ are *linearly separable* if $\exists\{\mathbf{w}, b\}$ such that $\langle \mathbf{w}, \mathbf{x} \rangle + b = 0$ separates the data, i.e.

$$\begin{aligned} \mathbf{x}_i \cdot \mathbf{w} + b &\geq 1 & \text{if } y_i = 1 \\ \mathbf{x}_i \cdot \mathbf{w} + b &\leq -1 & \text{if } y_i = -1 \end{aligned}$$

Definition Let d_+ (d_-) be the shortest distance from the separating hyperplane to a data point with + (-) label. The *margin* of the separating hyperplane w.r.t. the data is $d_+ + d_-$. If \mathbf{w} is the weight vector, then $d_+ = d_- = 1/\|\mathbf{w}\|$, so the margin $\gamma = 2/\|\mathbf{w}\|$.

Fact Let \mathcal{H} be the set of linear classifiers, and \mathcal{H}_γ be the set of linear classifiers with margin γ . Intuitively, \mathcal{H}_γ is smaller than \mathcal{H} . Let R be the radius of the smallest inclosing ball of the data, then

$$VC(\mathcal{H}_\gamma) \leq R^2 \mathbf{w} \cdot \mathbf{w} + 1, \tag{1}$$

independent of dimension.

3.6 Support Vector Machines (SVM)

The fact in (1) suggests optimizing the margin (SVM). Given $\{\mathbf{x}_i, y_i\} \in \mathbb{R}^N \times \{-1, 1\}$, find a good classification hyperplane given by the following optimization problem:

$$\begin{aligned} \min_{\mathbf{w}, b} \quad & \frac{1}{2} \|\mathbf{w}\|_2^2 \\ \text{Subject to} \quad & y_i (\langle \mathbf{w}, \mathbf{x} \rangle + b) \geq 1. \end{aligned} \tag{2}$$

We can write (2) as an unconstrained problem with the Lagrange multipliers. Define

$$L(\mathbf{w}, b, \alpha) = \frac{1}{2} \|\mathbf{w}\|_2^2 - \sum_i \alpha_i (y_i (\langle \mathbf{w}, \mathbf{x} \rangle + b) - 1),$$

then (2) becomes

$$\min_{\mathbf{w}, b} \max_{\alpha > 0} L(\mathbf{w}, b, \alpha) \tag{3}$$

We can view (3) as a two player game

- (1) If player A violates the constraint in (2), then player B can choose α such that the maximum goes to ∞ .
- (2) If player A satisfies the constraint in (2), then player B chooses $\alpha_i = 0$.